

# DE2 Electronics 2

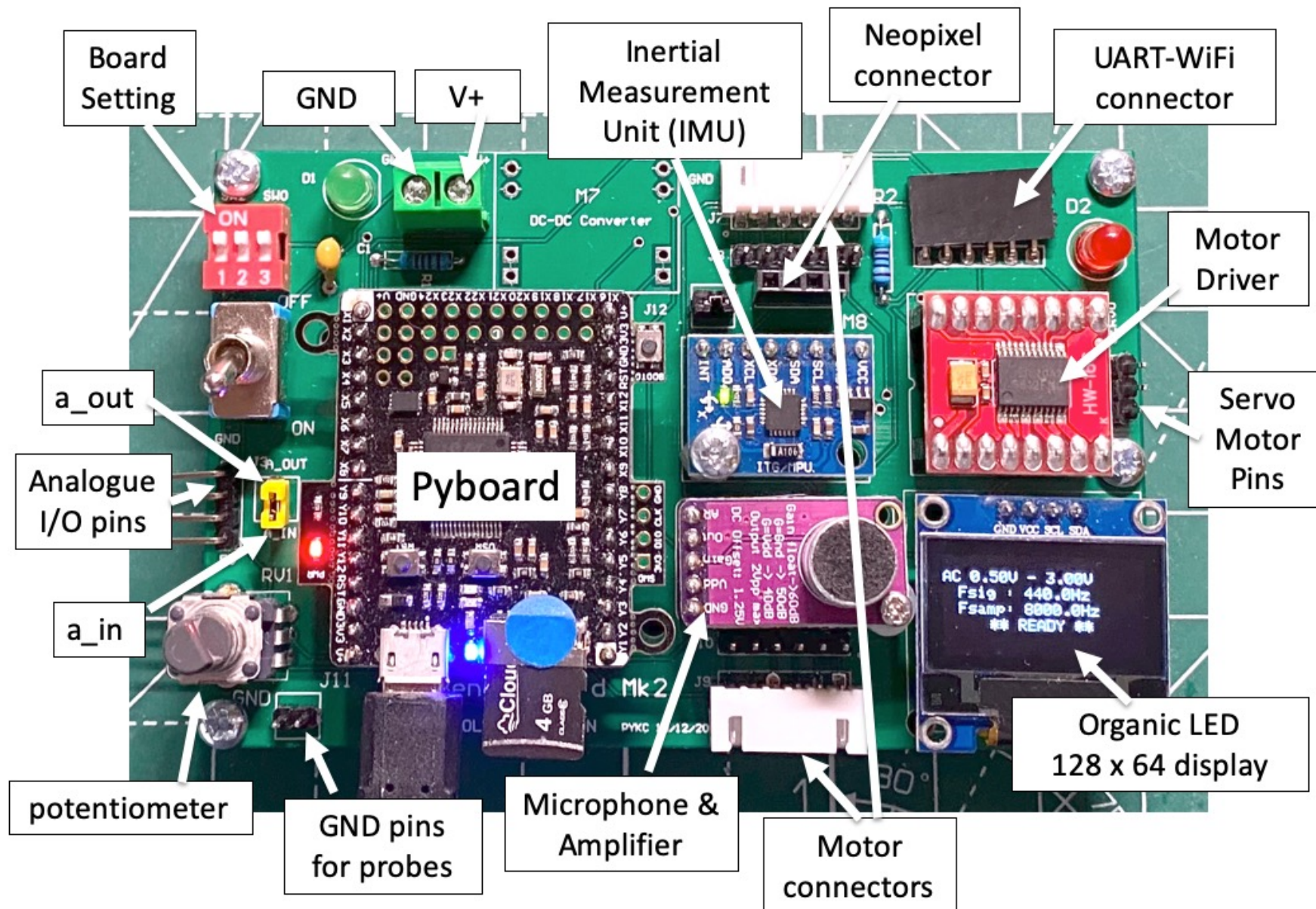
## Tutorial 2

### PyBench & Lab 2 Explained

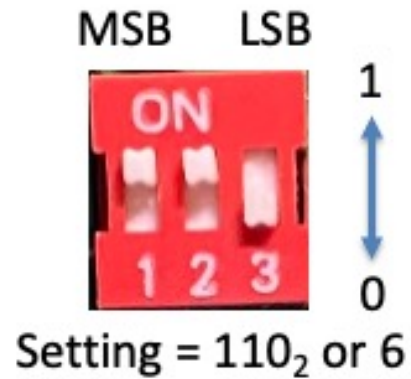
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URL: [www.ee.ic.ac.uk/pcheung/teaching/DE2\\_EE/](http://www.ee.ic.ac.uk/pcheung/teaching/DE2_EE/)  
E-mail: [p.cheung@imperial.ac.uk](mailto:p.cheung@imperial.ac.uk)

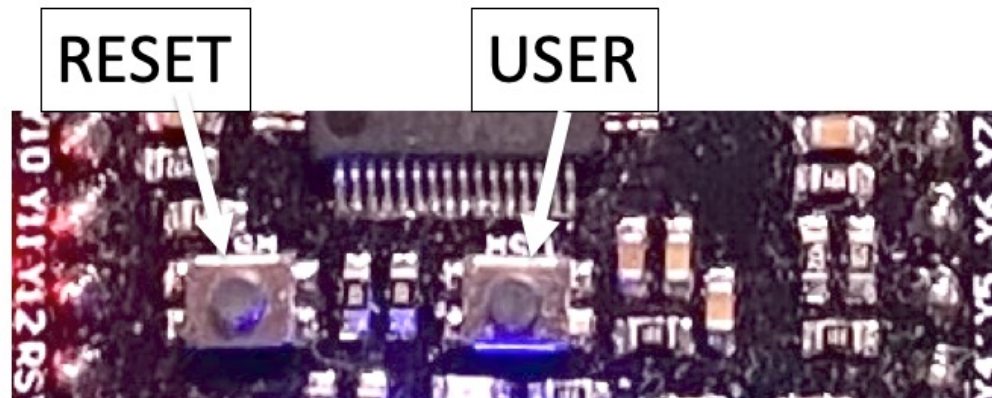
# What's on the Board



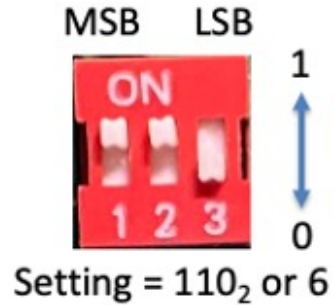
# Board setting



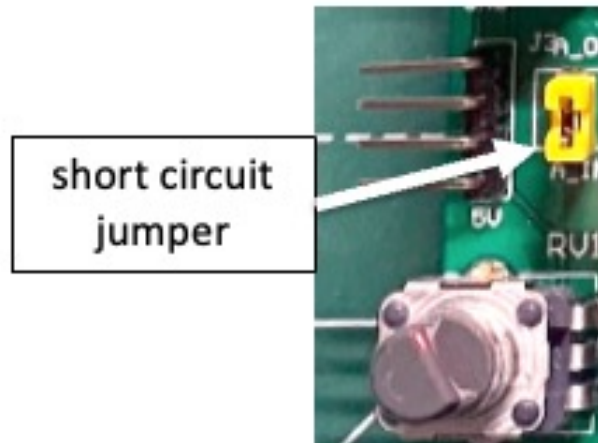
SW[2:0]	Function
000	Run user.py
001	Not used
010	Not used
011	<u>Wifi</u> module Test
100	Spectrum of mic signal
101	Bulb board test
110	Pybench board Test
111	Run pybench.py



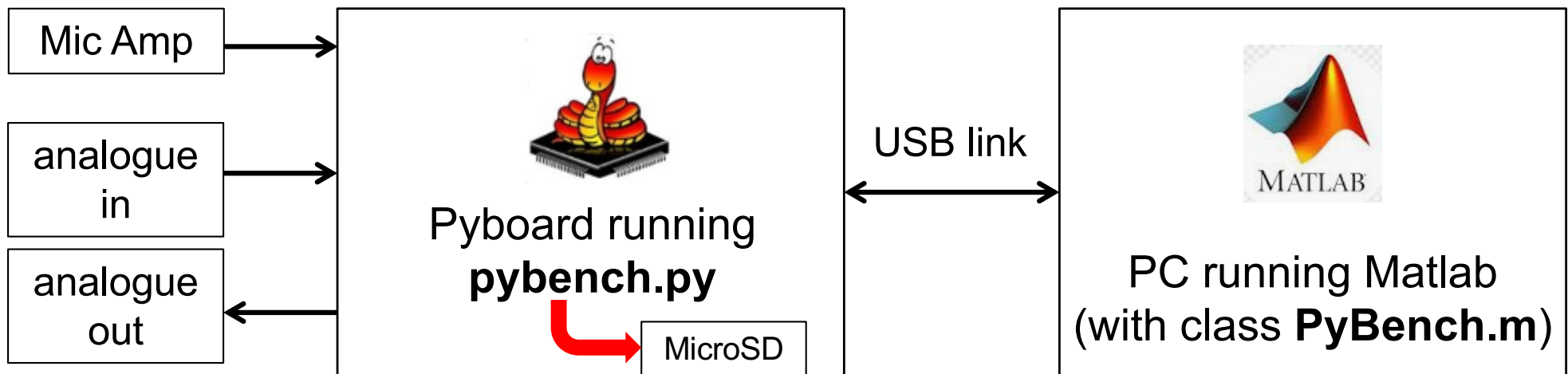
# Self-test – Verify PyBench system works



SW[2:0]	Function
000	Run user.py
001	Not used
010	Not used
011	<u>Wifi</u> module Test
100	Spectrum of mic signal
101	Bulb board test
110	Pybench board Test
111	Run pybench.py



# How PyBench works?



- ◆ Look for a serial link on computer:

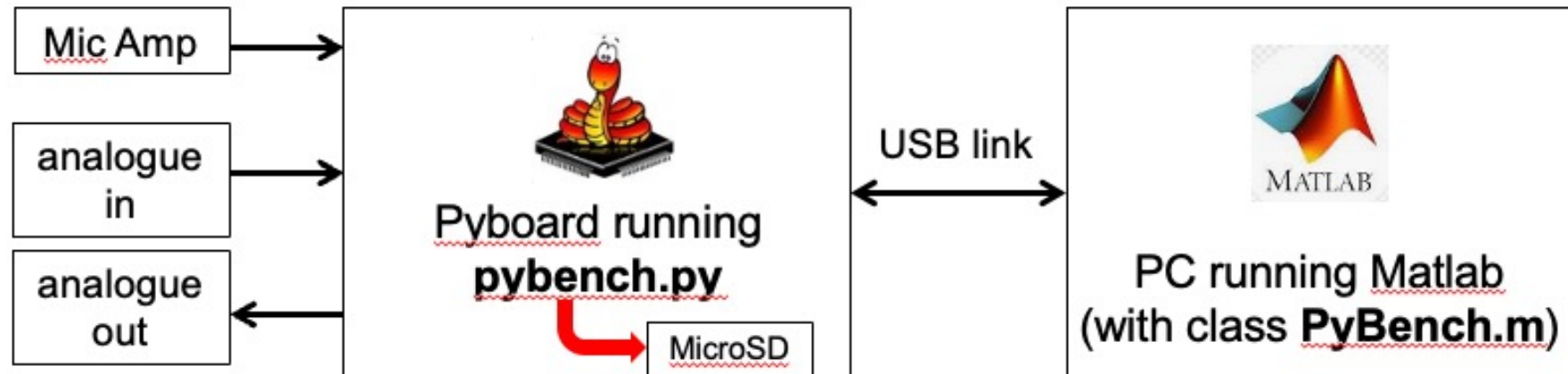
```
ports = serialportlist;    % find all serial port
```

- ◆ Last one is usually the one we want to use. The last port is given by: `ports(end)`.
- ◆ Create an object `pb` for the PyBench Board:

```
pb = PyBench(ports(end));  % create a PyBench object
```

- ◆ Control the Board via “methods”, e.g. `pb.set_max_v (2.5)`.

# pb.set\_max\_v(2.5) explained

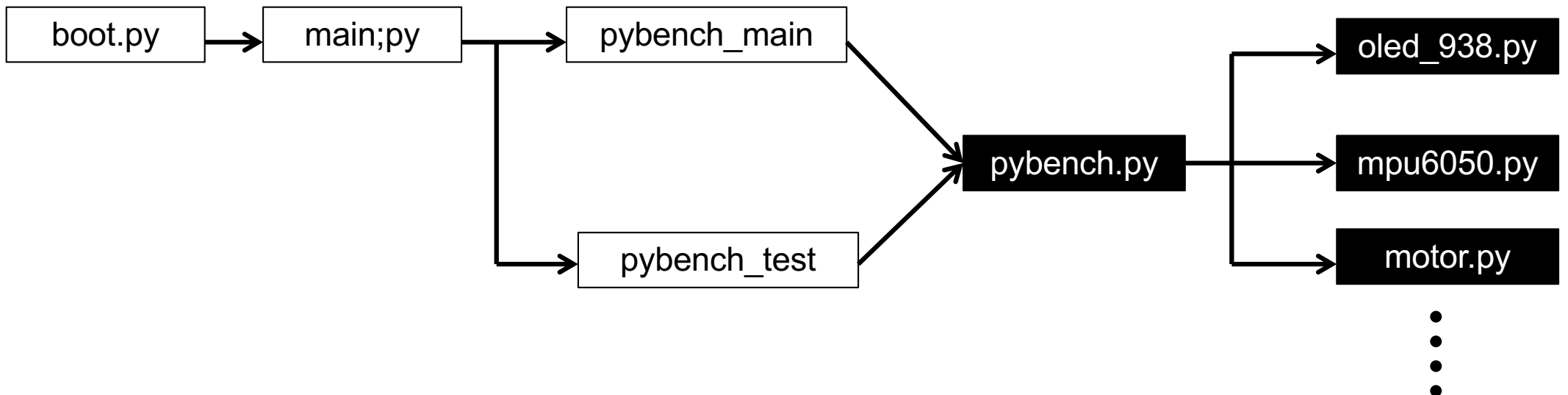


Here is what happens when you used this Matlab command: `pb = pb.set_max_v (2.5)`.

- ◆ PC sends three bytes to PyBench board via USB link as serial data. First byte is a command character. In this case, 'X', followed by the value of voltage as two bytes. First byte is  $\text{int}(4096 * (v/3.3) / 256)$ , and second byte is  $\text{int}(4096 * (v/3.3)) \bmod 256$ .
- ◆ All along, PyBoard is running a Python program (`pybench.py`) listening for a command. The BLUE LED is ON in this state. Waiting for an event such as a character to arrive is known as “**polling**”.
- ◆ When it receives the command (3 bytes), the `pybench.py` code sets the maximum voltage of the ADC to 2.5V.

# What are stored in the MicroSD card?

Program	Purpose
<a href="#">boot.py</a>	Boot file <u>specifying which is the main program.</u>
<a href="#">main.py</a>	Test the <u>DIP switch setting</u> and execute the corresponding <u>.py file.</u>
<a href="#">pybench_main.py</a>	The controlling program for <u>pybench</u> to <u>interpret commands.</u> Run if SW = 00.
<a href="#">pybench.py</a>	The <u>pybench</u> class library. Can be used in your own application program later.
<a href="#">pybench_test.py</a>	Self-test program for the <u>pybench</u> board to verify the hardware. Run if SW = 11.
<a href="#">oled_938.py</a>	OLED display driver class library.
<a href="#">font.py</a>	Character fonts used by <u>oled_938.py.</u>
<a href="#">mpu6050.py</a>	IMU driver class library – to communicate with the accelerometer and gyroscope.
<a href="#">drive.py</a>	Drive class for the motor driver chip TB6612.



# PyBench Methods

PyBench.m must be in the Matlab search path.

```
clear all
ports = serialportlist;    % find all serial port
pb = PyBench(ports(end)); % create a PyBench object with last port
```

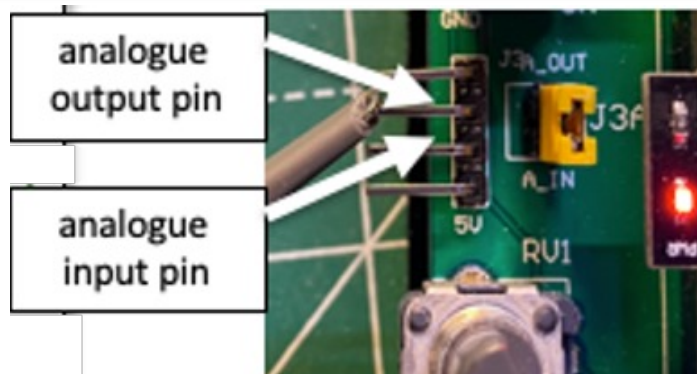
Methods	Purpose
<b>pb.set_sig_freq (f)</b>	Set signal frequency to f. $0.1 \text{ Hz} \leq f \leq 3000 \text{ Hz}$
<b>pb.set_samp_freq (f)</b>	Set sampling frequency to f. $1 \text{ Hz} \leq f \leq 30,000 \text{ Hz}$
<b>pb.set_max_v (v)</b>	Set maximum amplitude to v. $0 \leq v \leq 3.3$
<b>pb.set_min_v (v)</b>	Set minimum amplitude to v. $0 \leq v \leq 3.3$
<b>pb.set_duty_cycle (d)</b>	Set duty cycle of a square signal to d. $0 \leq d \leq 100$
<b>pb.dc (v)</b>	Output a dc voltage v. $0 \leq v \leq 3.3$
<b>pb.sine ( )</b>	Output a sinusoidal signal at set signal frequency between max_v and min_v.
<b>pb.triangle ( )</b>	Output a triangular signal at set signal frequency between max_v and min_v.
<b>pb.square ( )</b>	Output a square signal at set signal frequency between max_v and min_v, with the set duty cycle.
<b>v = pb.get_one ( )</b>	Capture one sample v from analogue input. $0 \leq v \leq 3.3$
<b>data = pb.get_block (n)</b>	Capture n samples from analogue input. $0 \leq \text{data} \leq 3.3$
<b>data = pb.get_mic (n)</b>	Capture n samples from microphone. $0 \leq \text{data} \leq 3.3$



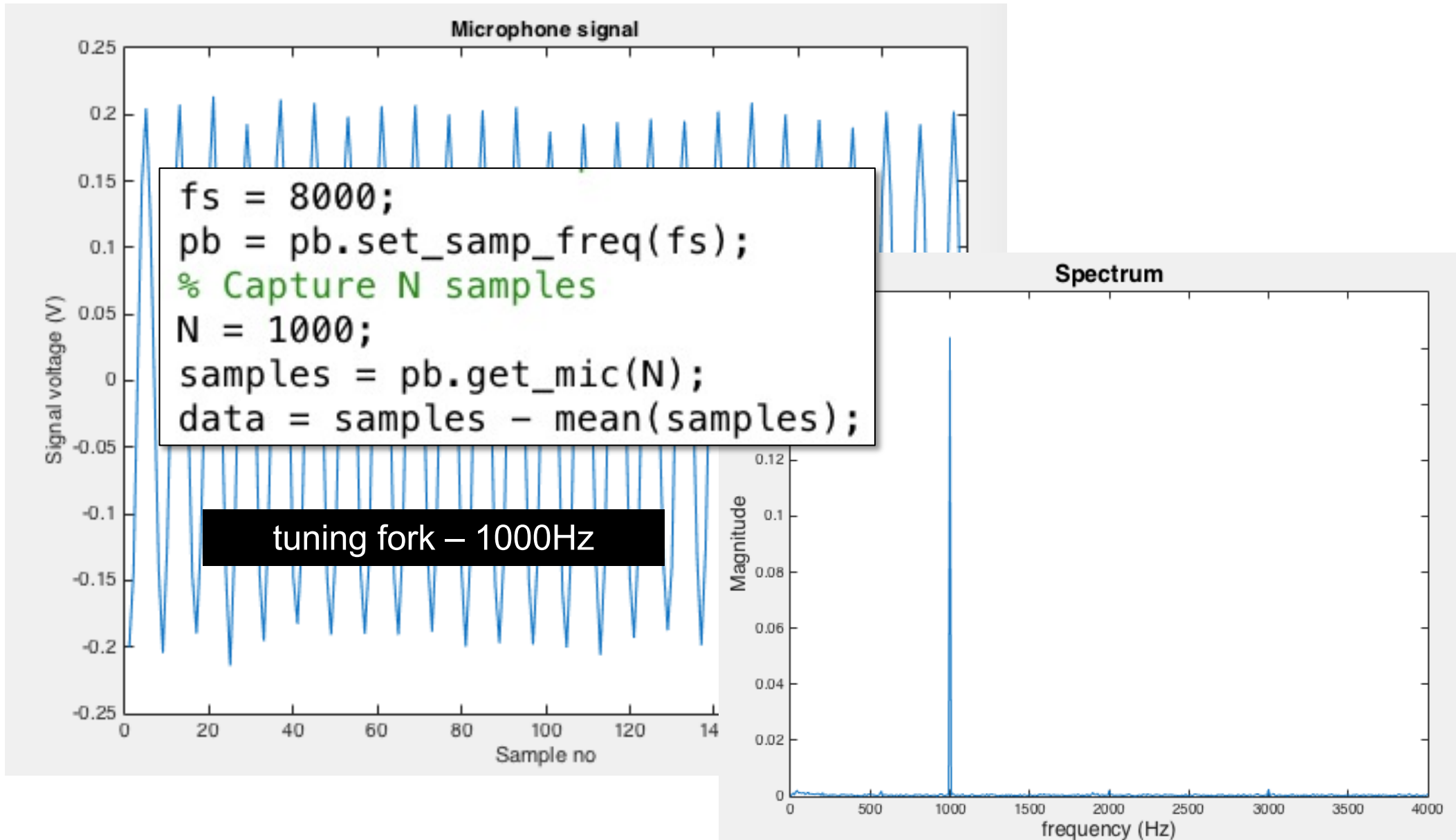
# Lab 2 Task 2 – Generate and Capture Signals

```
% Lab 2 – Task 2 – Signal generation and capture with PyBench
%
clear all
ports = serialportlist;      % find all serial ports
pb = PyBench(ports(end));    % create a PyBench object
% Set the various parameters
f = 440;                     % signal frequency (Hz)
fs = 8000;                   % sampling frequency (Hz)
pb = pb.set_sig_freq(f);     % set signal frequency
pb = pb.set_samp_freq(fs);   % set sampling frequency
pb = pb.set_max_v(3.0);      % set maximum voltage (V)
pb = pb.set_min_v(0.5);      % set minimum voltage (V)
pb = pb.set_duty_cycle(50);  % set duty cycle (%)
% Generate a signal
pb.sine();

% Capture N samples
N = 1000;
samples = pb.get_block(N);
data = samples - mean(samples);
% plot data
figure(1);
plot(data(1:200), 'o');
hold on
plot(data(1:200));
xlabel('Sample no');
ylabel('Signal voltage (V)');
title('Captured signal');
hold off
% find spectrum
figure(2);
plot_spec(data, fs);
```



## Lab 2 Task 3 – Microphone signal



## Lab 2 Task 3 – Repeated capture & plot spectrum

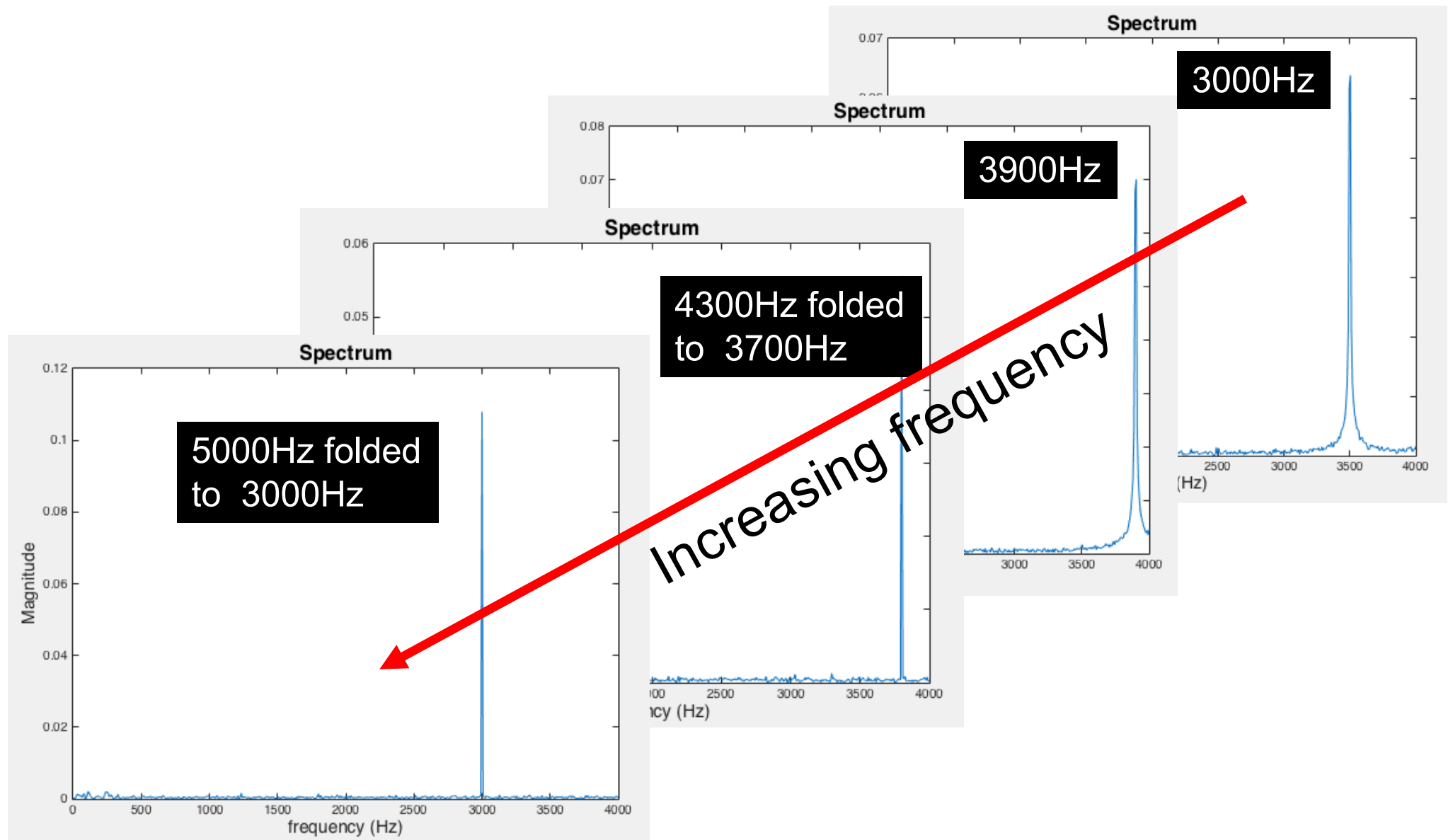
```
% repeat capture and plot spectrum
while true
    samples = pb.get_mic(N);
    data = samples - mean(samples);
    figure(2)
    clf;
    plot_spec(data, fs);
end
```

**Warning:** Running Matlab in an infinite loop may prevent you from re-gaining control over Matlab or even your computer. There are two things you may try if you want to get back control: 1) Type CTRL+C in the Command Window to interrupt Matlab; 2) kill the Matlab process and restart it again.

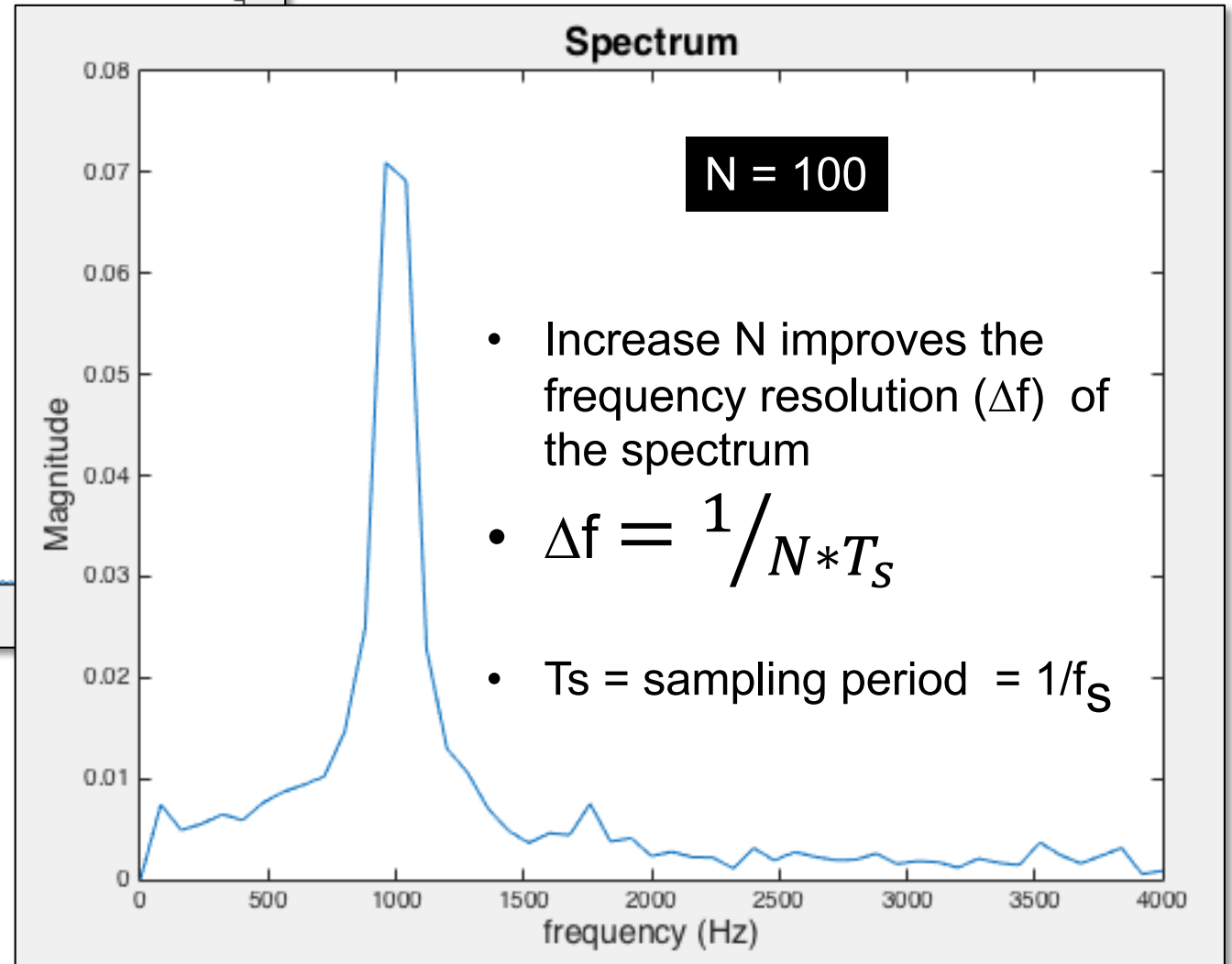
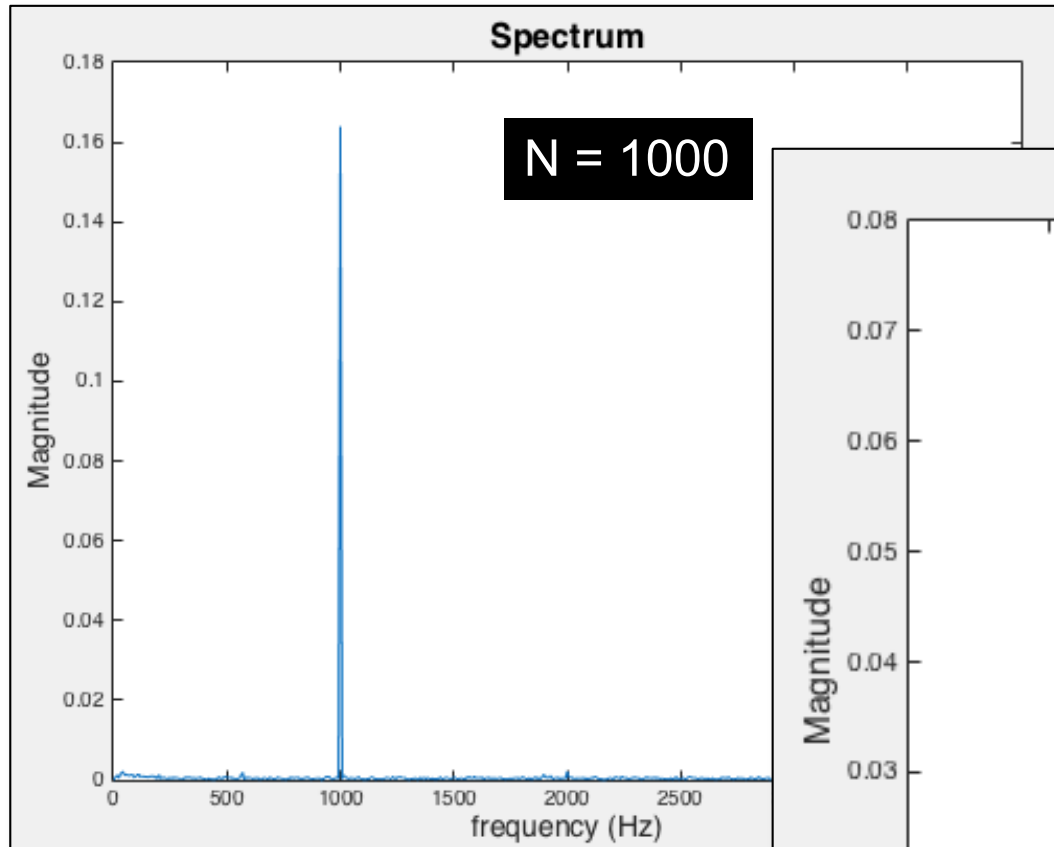
Recover from lost of serial communication:

1. Disconnect/reconnect USB; kill & restart Matlab
2. CTRL+C in command window, then type `fclose(pb.usb)` to shut down usb communication port

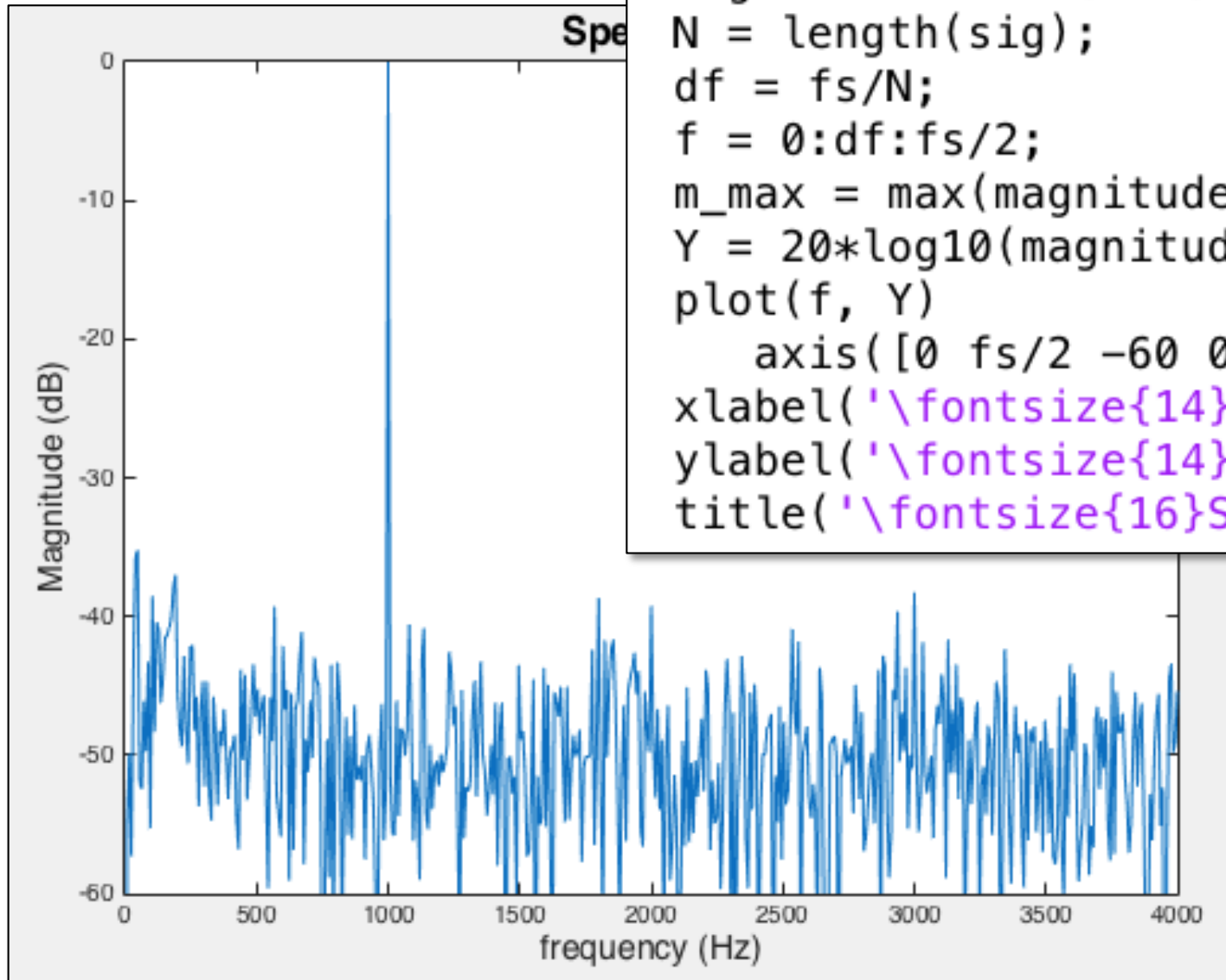
# Lab 2 Task 3 – Demonstrate spectral folding (aliasing)



# Lab 2 Task 3 – Effect of changing N – no of samples to analyse

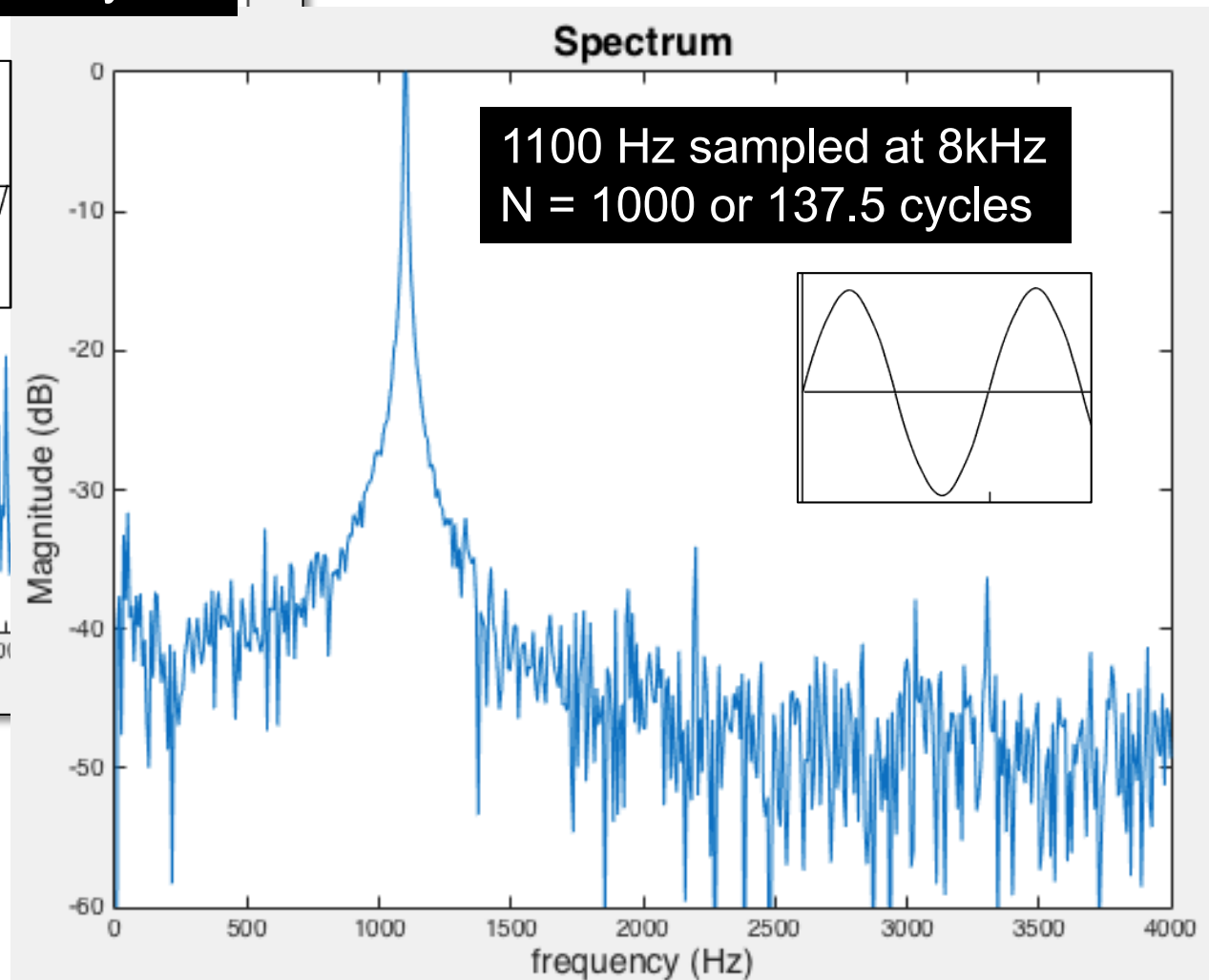
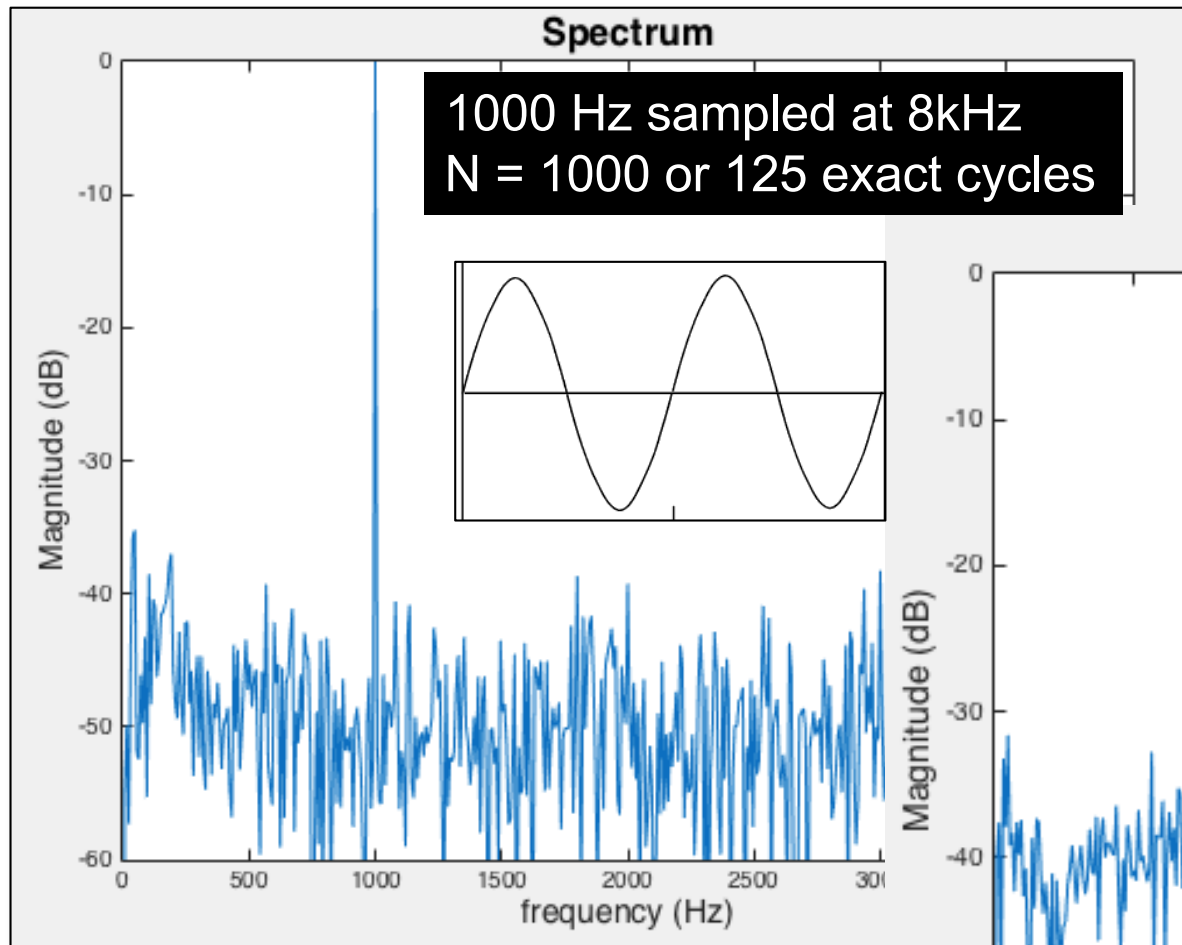


## Lab 2 Task 4 – Magnitude in dB

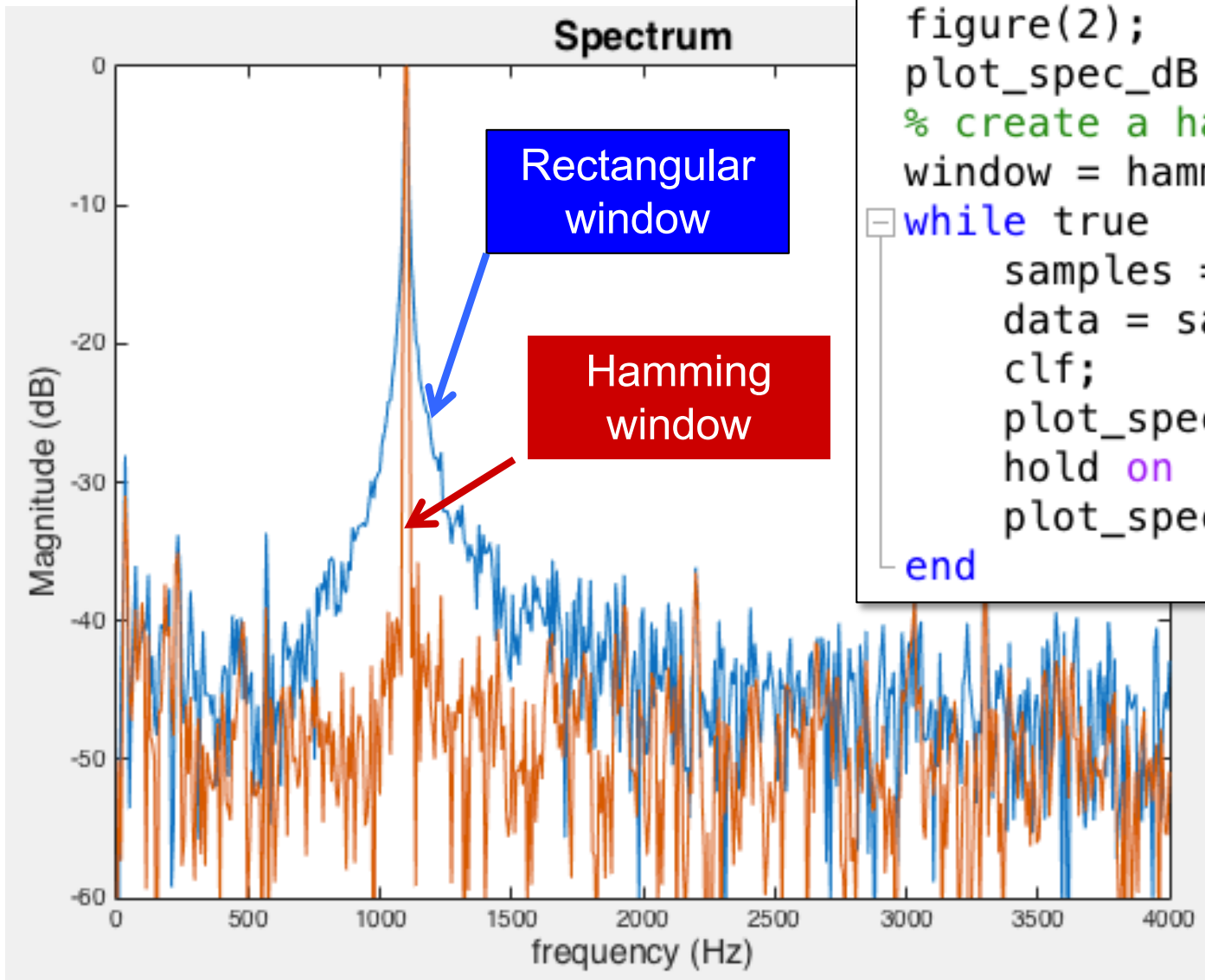


```
magnitude = abs(fft(sig));  
N = length(sig);  
df = fs/N;  
f = 0:df:fs/2;  
m_max = max(magnitude);  
Y = 20*log10(magnitude(1:length(f))/m_max);  
plot(f, Y)  
    axis([0 fs/2 -60 0]);  
xlabel('\fontsize{14}frequency (Hz)')  
ylabel('\fontsize{14}Magnitude (dB)');  
title('\fontsize{16}Spectrum');
```

## Lab 2 Exercise 4 – Windowing effect



# Lab 2 Task 4 – Rectangular vs Hamming Window



```
% find spectrum
figure(2);
plot_spec_dB(data,fs);
% create a hamming window
window = hamming(length(data));
while true
    samples = pb.get_mic(N);
    data = samples - mean(samples);
    clf;
    plot_spec_dB(data,fs);
    hold on
    plot_spec_dB(data.*window,fs);
end
```



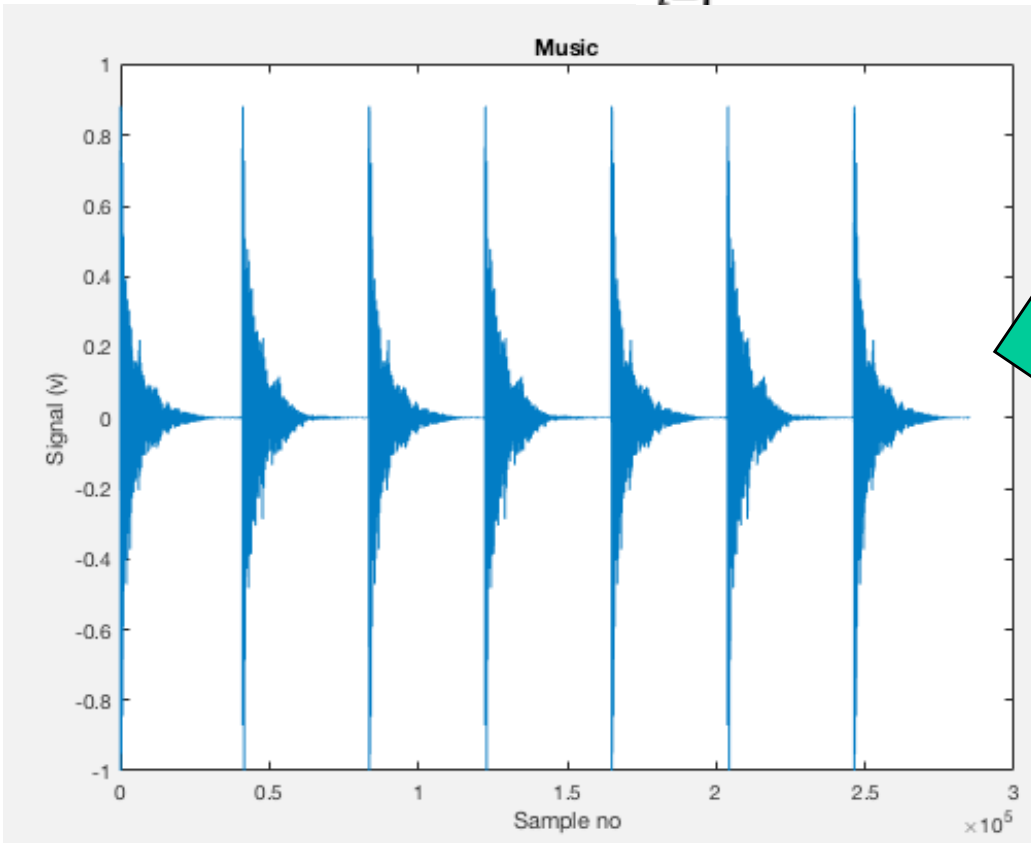
## Lab 2 Task 5 – Calculate energy in 20ms segment

```
% Divide signal into segments of length N
T = 0.02;           % duration of each segment in seconds
N = fs*T;          % number of samples in each segment
E = [];
for i=1:N:length(sig)-N+1
    seg = sig(i:i+N-1);
    E = [E seg'*seg];
end
% plot the energy graph and the peak values
figure(2);
clf;
x = 1:length(E);
plot(x, E)
xlabel('Segment number');
ylabel('Energy');
hold on
% Find local maxima
[pks locs] = findpeaks(E);
plot(locs, pks, 'o');
hold off
% plot spectrum of energy
figure(3)
plot_spec(E - mean(E), 1/T);
```

$\sum_{i=1}^N x^2(t)$  where N is the number of samples in 20ms

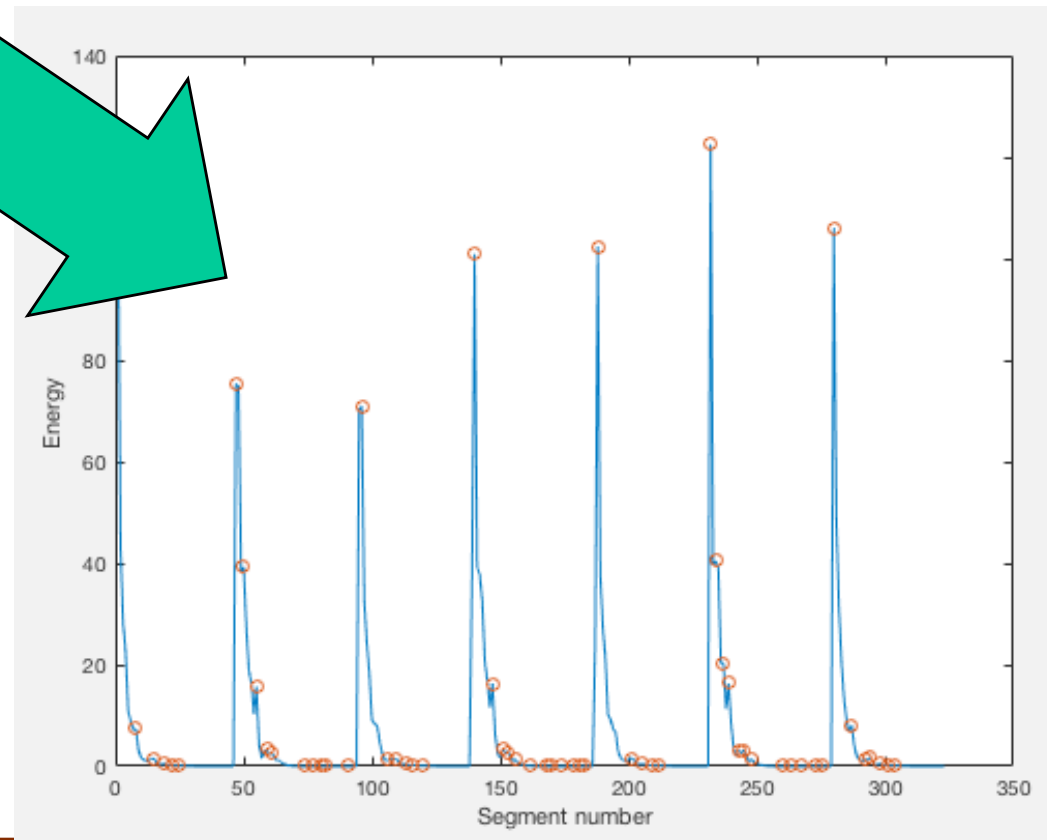
# Lab 2 Task 5 – Analyse beat of drum beats (1)

$$\sum_{i=1}^N x^2(t) \quad \text{where } N \text{ is the number of samples in 20ms}$$



Signal  $x(t)$

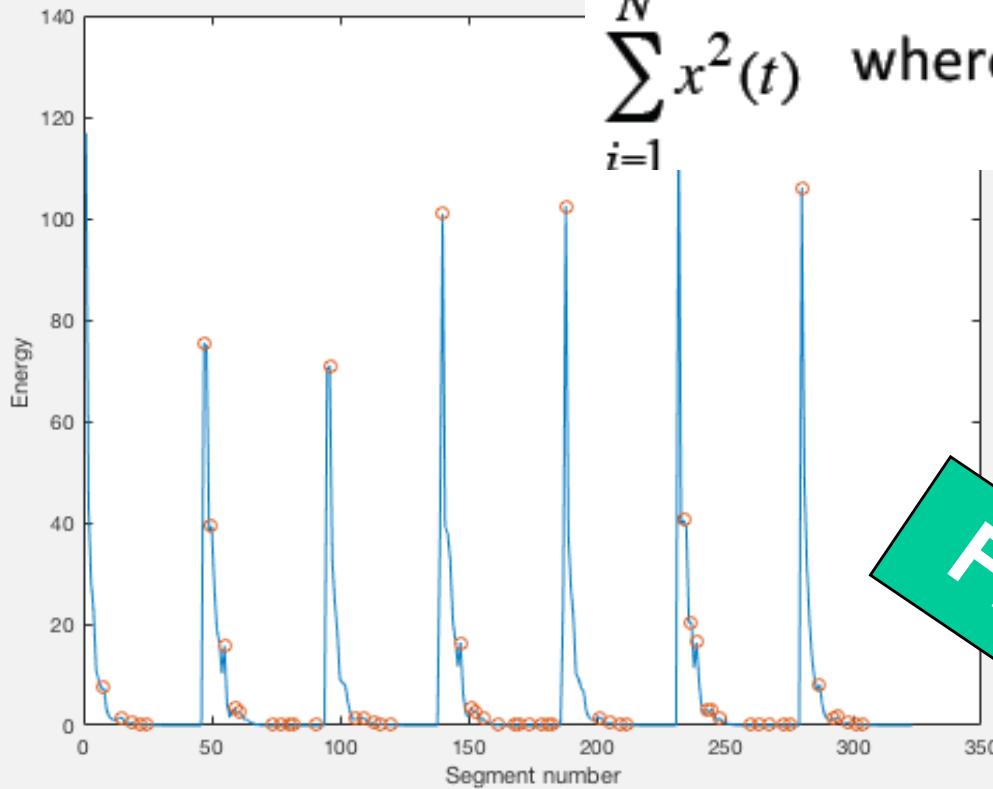
Energy of signal



# Lab 2 Task 5 – Analyse beat of drum beats (2)

$$\sum_{i=1}^N x^2(t)$$

where N is the number of samples in 20ms



Energy vs time

Spectrum of energy

